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| **Python Level 1 with Virtual Robotics**  **Mission 7 Objective 2 Line Sensor Readings** | | | **Name:** | |
| Use this document to chart the line sensor readings while rotating around the compass rose.   * Look for line sensor readings where the left and right are different. * The right reading will become the left reading when the ‘bot is on the next compass point. * Your readings may be a little different from another person’s bot. | | | | |
|  | **Compass Point** | **Left Reading** | | **Right Reading** |
|  | **West** | 2481 | | 3019 |
|  | **North West** | 3019 | |  |
|  | **North** |  | |  |
|  | **North East** |  | |  |
|  | **East** |  | |  |
|  | **South East** |  | |  |
|  | **South** |  | |  |
|  | **South West** |  | |  |